

JSDA⁺

JSDE⁺

AC Servo System





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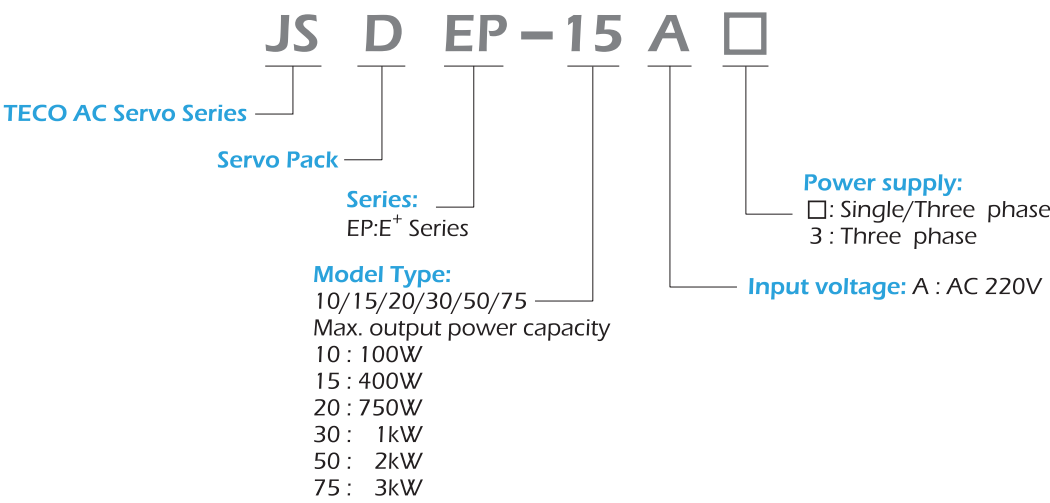
JSDE⁺ Series

Standard Servo Amplifier

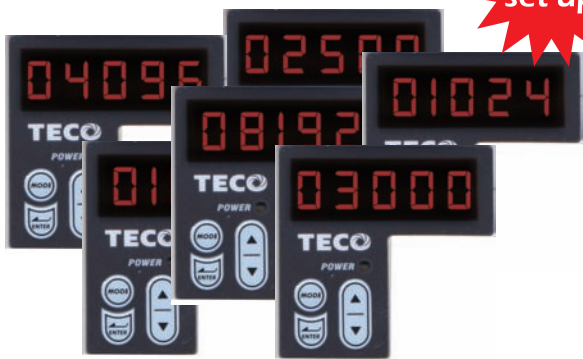


Frame	1				2	
JSDEP	10A	15A	20A	30A	50A3	75A3
Max. Capacity	100W	400W	750W	1kW	2kW	3kW

Model Designation



Friendly Interface for Scaling of Encoder Feedback

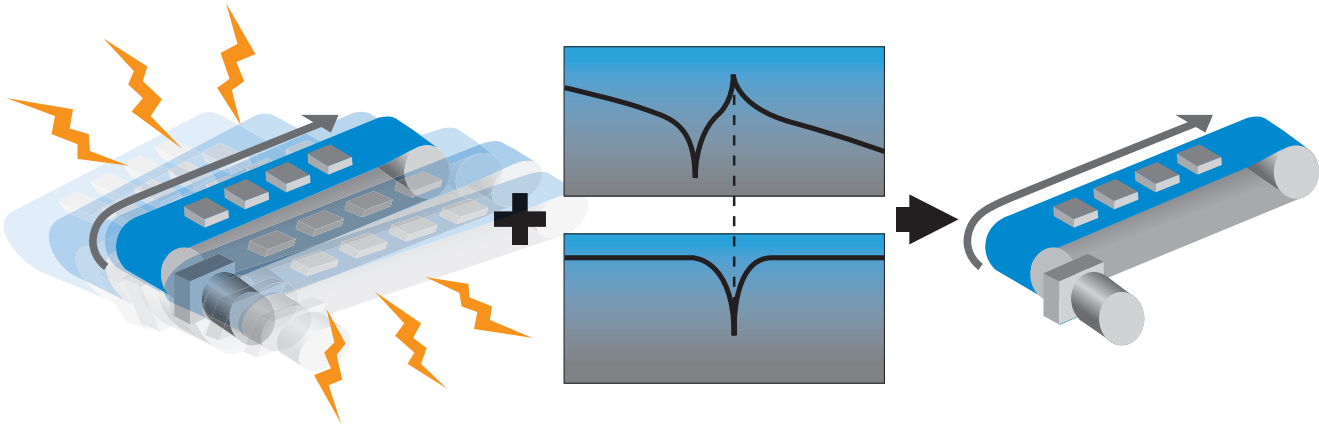


Easy set up

The scaling of the encoder feedback pulse could be set by parameter, with a range from 0 to the encoder maximum pluse per rotation.

Notch Filter

Notch filter can be used to reduce or eliminate the vibration caused by mechanical resonance.



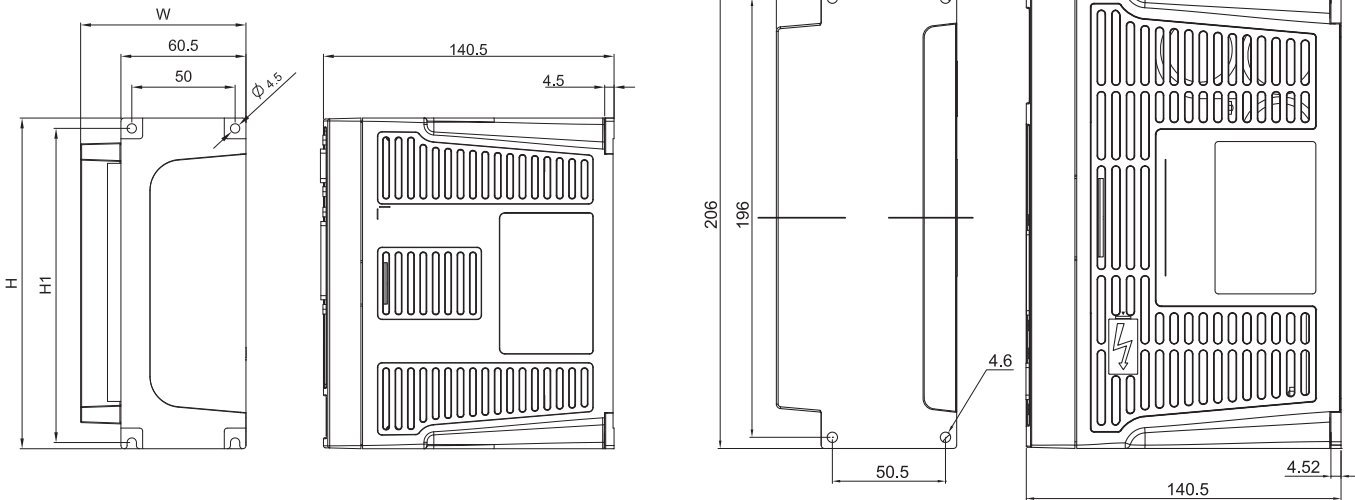
JSDE⁺ Dimension

Model	H	H1	W
JSDEP-10A/15A	160	152	67
JSDEP-20A/30A	160	152	80

Unit:mm

Model	H	H1	W
JSDEP-50A3/ 75A3	206	195	80

Unit:mm



JSDE⁺ Specifications

	Servo Amplifier model JSDEP-□□□□		10A	15A	20A	30A	50A3	
Basic Specification	Max. Applicable Servo Motor Capacity[KW]		0.1	0.4	0.75	1.0	2.0	
	Continuos Current output[A rms]		0.94	2.5	4.4	5.16	9.5	
	Max. output Current[A rms]		2.82	7.5	13.2	15.5	28.5	
	Power Supply	Main Circuit R, S, T	Single Phase/Three Phase AC 170 ~ 253V					Three Phase AC 170 ~ 253V
			50 / 60Hz ±5%					
	Cooling System		Natural Air Circulation			Fan Cooling		
	Control Mothed		Three Phase full-wave rectification IGBT-PWM(SPWM)					
	Feedback[Encoder Resolution]		Incremental Encoder : 2500ppr / 8192ppr					
Common Function	LED Display		Charge / Power lamps ; Five 7-segment LEDs ; Four function keys					
	Control Mothed		Position[External Pulse Command/Internal Pulse Command], Speed/Torque and Dual control mode(P/S、S/T、P/T)					
	Regenerative Discharge		Built-in braking transistor (External braking resistor available)					
	Protective Function		Under voltage, Over voltage, Over load, Over current, Encoder error, Abnormal DI/DO programming, Memory abnolal, Emergency stop, Pulse deviation, Over speed, CPU abnomal, Limit switch error, Over heat...etc.					
	Communication interface		RS-232 / RS-485 (Modbus protocol)					
Position control	Command Source		External pulse train / Internal parameter (32 steps)					
	Input Signals	Type	Positive / Negative edge trigger : Sign+Pulse train, CCW+CW pulse train, 90° phase difference 2-phase pulse(A phase+B phase)					
		Form	Line Driver (+5V Level) 、 Open Collector (+5 ~ +24V Level)					
		Frequency	4Mpps(Line driver) / 200Kpps(Open collector)					
	Electronic Gear Ratio		1/200 ≦ A/B ≦ 200 (A=1 ~ 50000 ; B=1 ~ 50000)					
	Position Time Constant		smoothing : 0 ~ 10sec					
	Final Position Tolerance		0 ~ 50000 Pulse					
	Feed Forward Compensation		0 ~ 100 %					
Speed control	Homing Function		Set by parameter					
	Command Source		External analog signal / Internal parameter(3 speed set-up)					
	Analog Input Signals	Voltage Range	0 ~ ±10Vdc / 0 ~ 4500rpm (Set by parameter)					
		Impedance	10KΩ					
	Speed Control Range		1 : 5000 (Internal command) / 1 : 2000 (External command)					
	Speed Fluctuation Rate		Load fluctuation : 0 ~ 100% ±0.03% or less (at rated speed)					
			Power fluctuation : ±10% ±0.2% or less(at rated speed)					
			Ambient temperature fluctuation : 0 ~ 50°C ±0.5% or less (at rated speed)					
Accel/Decel. Time Constant		Linear : 0 ~ 50sec, S-Curve : 0 ~ 5sec, Smoothing : 0 ~ 10sec						
Torque control	Frequency Characteristic		600Hz (at J _L =J _M)					
	Torque Limit Operation		External analog signal / Internal parameter					
	Zero Speed / Speed Reach Range		0 ~ 4500rpm (Set by parameter)					
	Command Source		External analog signal					
	Analog Input Signals	Voltage Range	0 ~ ±10Vdc / 0 ~ ±300%					
		Impedance	10KΩ					
	Accel/Decel. Time Constant		Linear : 0 ~ 50sec					
	Speed Limit Operation		External analog signal / Internal parameter					
I/O signals	Torque Reach Range		0 ~ 300% (set by parameter)					
	Position Output	Output Signal	Phase A、B、Z Line Driver / Phase Z Open Collector					
		Scaling of encoder feedback pulse	Set up of any value is enabled (encoder pulse is the max.)					
	Digital Input [NPN/PNP]	Programmable 6 Points	Servo on, Alarm reset, P/PI switching, Forward/Reserve limit switch, External torque limit, Pulse deviation clear, Servo lock, Emergency stop, Speed command selection, Control mode switching, Pulse command inhibit, Gain switching, Electronic gear ratio setting, Internal pulse command trigger, Internal pulse sommand pause, Homing mode positioning, External reference signal, Internal position command switching, Speed/Torque command reverse, Torque mode forward / reverse start...etc.					
Digital Output [Photocoupler]	Programmable 3 Points	Servo ready, Servo alarm, Zero speed, Brake interlock, Speed reach, Positioning completed, Homing completed, Torque reach						
Enviroment	Installation Site		Indoor location(Avoiding direct sunshine) No corrosive liquid and gas(avoiding oil mist, flammable gas, dust)					
	Aititude		Altitude 1000M or lower above sea level					
	Temperature		Operating temperatue : 0 ~ 50°C ; Storage temperature : -20 ~ +65°C					
	Humidity		90%RH or less(No condensation)					
	Vibration		10 ~ 57Hz : 20m/s ² ; 57 ~ 150Hz : 2G					
Certification		CE	In compliance with EN61800-3 and EN61800-5-1					
		UL	UL508C					

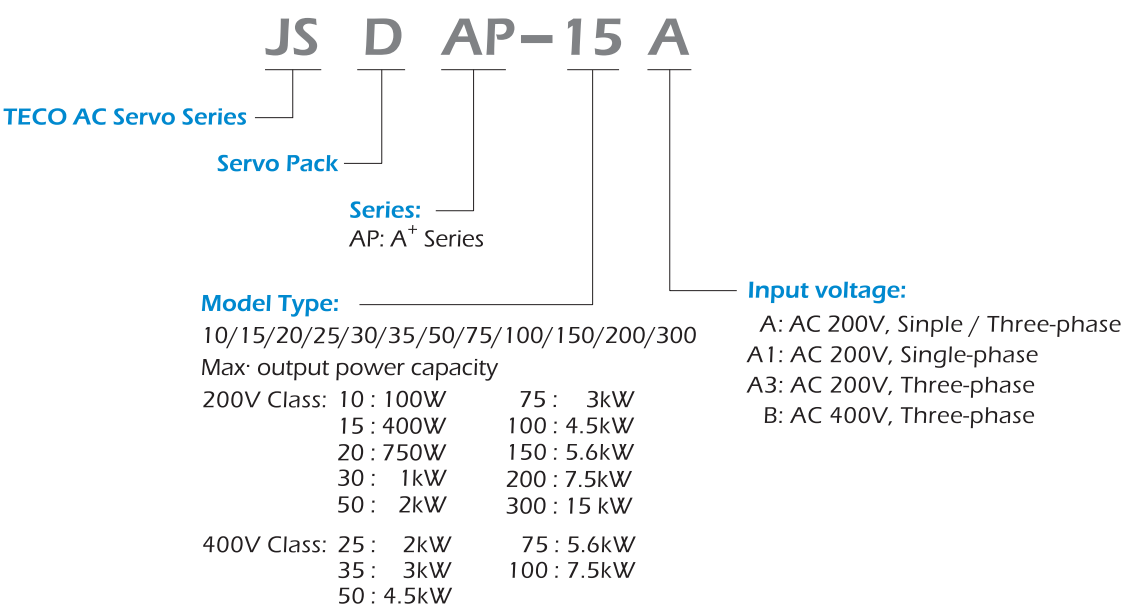
JSDA⁺ Series

Advanced Servo Amplifier

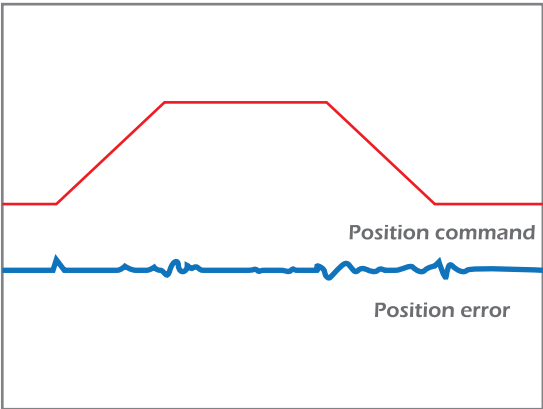


Frame	1				2				3		4	
200V	10A	15A	20A	30A	50A3	75A3	100A3	150A3			200A3	300A3
400V				25B	25B	35B	50B	75B	100B			
Max. Capacity	100W	400W	750W	1kW	2kW	3kW	4.5kW	5.6kW	7.5kW	7.5kW	7.5kW	15kW

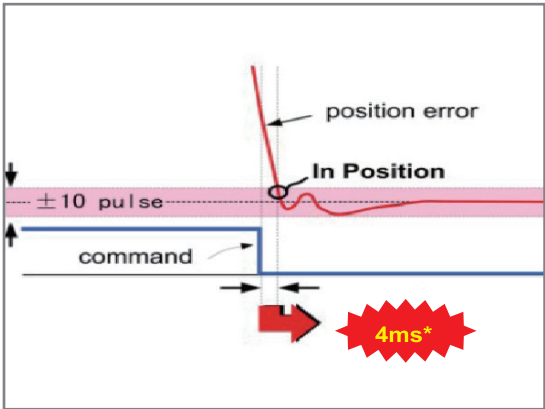
Model Identification



Excellent Performance



Performance of the position doubled in comparison with current models by adoption of the optimized position and speed control algorithm.



A optimized method drastically shortens positioning settling time for equipment.
*Determined under field conditions.

High Resolution Encoders



Built-in Regenerative Resistor



*Built-in regenerative resistor below JSDAP-150A3

Battery Module for Absolute Encoder



Frame 1



Frame 2



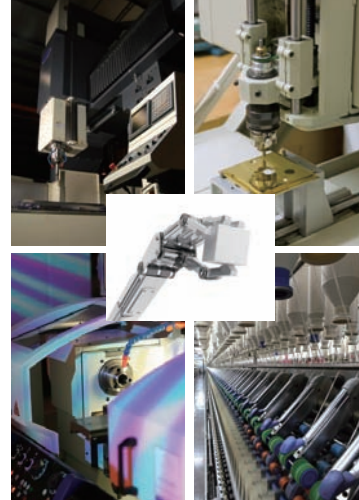
Frame 3

Auto Motor Recognition

Through 17-bit and 15-bit encoders, servo motor can be identified.



Applications



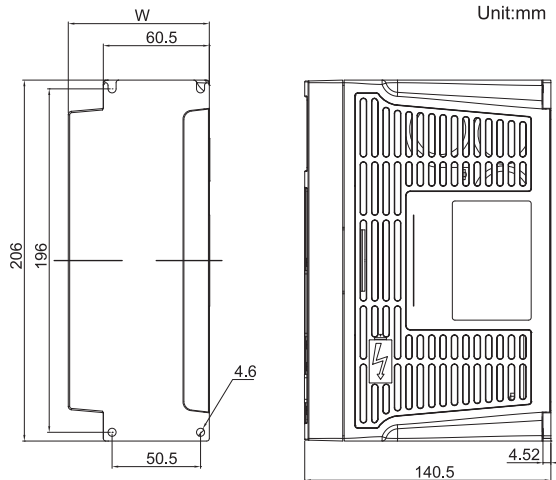
- Mechanical arm
- Engraving machine
- Computerized flat knitting machine
- CNC Lathe machine
- CNC wire cutting machine
- Injection molding machine
- PCB Router machine

JSDA⁺ Dimension

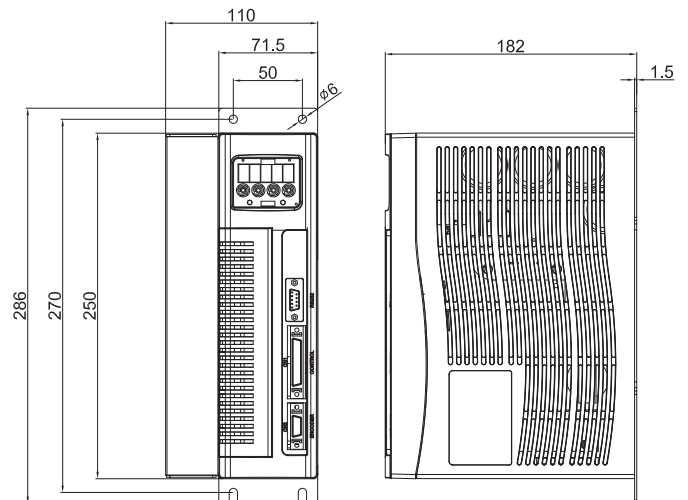
JSDAP-10A/15A/20A/30A

Model	W
JSDAP-10A/15A	69.5
JSDAP-20A/30A	80.5

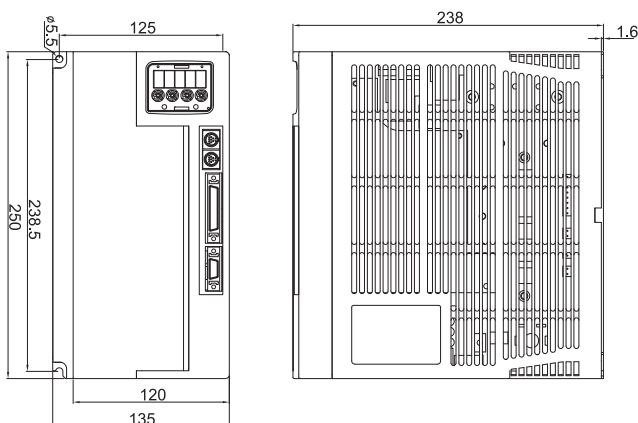
Unit:mm



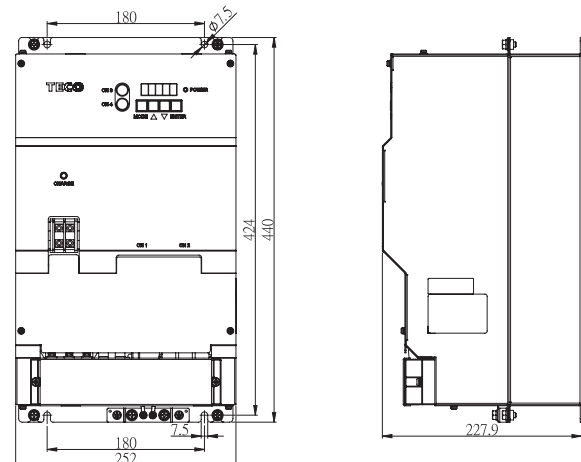
JSDAP-50A3/75A3/100A3/25B/35B/50B



JSDAP-150A3/75B/100B



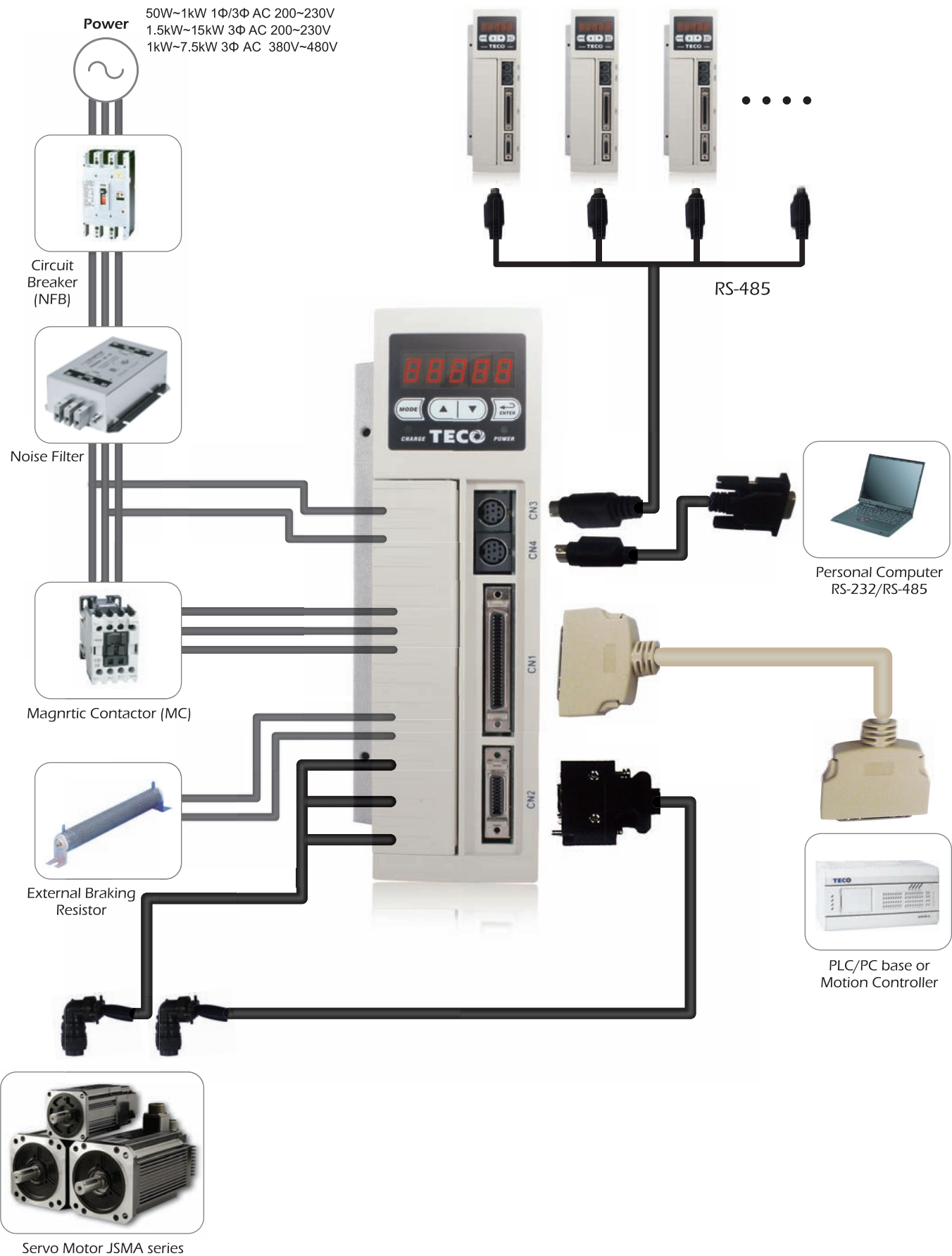
JSDAP-200A3/300A3

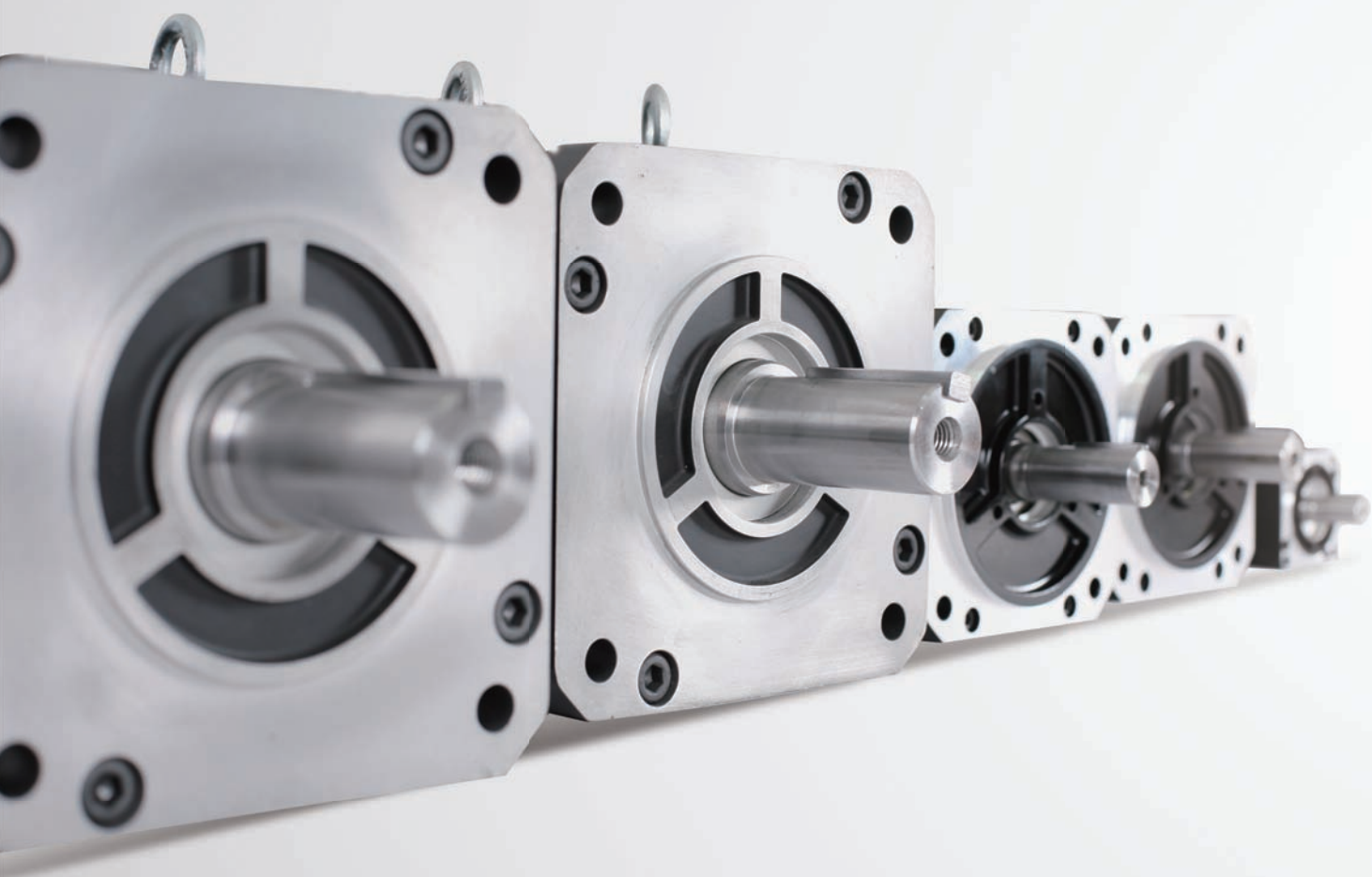


JSDA⁺ Specifications

Servo Drives for JSDAP-□□□□			200V Class									400V Class						
			10A	15A	20A	30A	50A3	75A3	100A3	150A3	200A3	300A3	25B	35B	50B	75B	100B	
Basic Specifications	Max. Applicable Servo Motor Capacity [KW]		0.1	0.4	0.75	1	2	3	4.5	5.6	7.5	15	2	3	4.5	5.6	7.5	
	Continuous Output Current [A rms]		0.94	2.5	4.4	5.16	9.5	15	23	33.2	42.1	78	6	8	11.5	16	22	
	Max. Output Current [A rms]		2.82	7.5	13.2	15.5	28.5	42	59.8	86.3	109.5	170	15.6	20.8	29.9	41.6	57.2	
	Power Supply	Main Circuit R/S/T	Single/Three-Phase AC 200~230V									Three-Phase AC 200 ~ 230V						
		Control Circuit r/s	50/60Hz ±5%										Three-Phase AC 380~480V					
			Single-Phase AC 200 ~ 230V										DC 24V, ±10%					
			50/60Hz ±5%															
Cooling System		Natural Air Cooling		Fan Cooling														
Control of Main Circuit		Three-phase full-wave rectification IGBT- SVPWM Control(Sine-wave current drive way)																
Feedback (Encoder Resolution)		Incremental type : 2500ppr / 8192ppr / 15-bit (ABS) / 17-bit /17-bit (ABS)																
LED Display		Main/ control circuit power indicator; 5 digital seven-segment display ; four function key																
Internal Functions	Control Mode		Position (External pulse command), Position (Internal position command), Speed, Torque and Dual mode switching (Position/Speed,Speed/Torque, Position/ Torque)															
	Regenerative Brake		Built-in braking transistor and resistor / External braking resistor									Built-in braking transistor resistor		Built-in braking transistor and resistor / External braking resistor				
	Dynamic Brake		Built-in dynamic braking; Power-off, Servo-off, Drive disable and Alarm occurred															
	Protection Function		Low Voltage, Over Voltage, Overload, Over Current, Encoder signal error, Multi-function contact setting error, Memory error, Emergencystop, Position error, Motor Over Speed, CPU error, Drive disable, Overheat. 16 Types of Alarm Functions															
	Communication Interface		RS-232 / RS-485 (Modbus protocol)															
	Command Source		External command/ Pulse command / 32-Stage internal register command															
Position Control Mode	Input Signals	Type	Positive/Negative Edge Trigger Type : Direction + Pulse, CW/CCW Pulse , Phase difference pulse (A Phase + B Phase)															
		Form	Line Driver (+5V), Open Collector (+5 ~ +24V)															
		Frequency	4Mpps(Line Driver) / 200Kpps(Open Collector)															
	Electronice Gear Ratio		1/400≤ A/B≤ 400 (A=1 ~ 50000 : B=1 ~ 50000)															
	Position Time Constant		Ripple Time Constant : 0 ~ 10sec															
	Final Position Tolerance		0 ~ 50000 Pulse															
	Feed Forward Compensation		0 ~ 100 %															
	Homing Function		Set by internal parameters															
Speed Control Mode	Command Source		External analog Command / 3-Stage internal speed command															
	Analog Input Signals	Voltage Range	0 ~ ±10Vdc / 0 ~ 6000rpm (set by internal parameters)															
		Impedance	10KΩ															
	Speed Control Range		1 : 5000 (internal speed command) / 1 : 2000 (external analog command)															
	Speed Fluctuation Rate		±0.03% or less at Load fluctuation 0 to 100% (at Rated Speed) ±0.2% or less at power fluctuation ±10% (at Rated Speed) ±0.5% or less at ambient temperature fluctuation 0℃ to 50℃ (at Rated Speed)															
	Accel/Decel. Time Constant		Linear : 0 ~ 50sec ; S-curve : 0 ~ 5sec ; Ripple : 0 ~ 10sec															
	Frequency Characteristics		800Hz (J _L = J _M)															
	Torque Limit Operation		External analog command / Set by internal parameters															
Zero Speed/ Speed Reach Range		0 ~ 4500rpm (Set by internal parameters)																
Torque Control Mode	Command Source		External analog command															
	Analog Input Signals	Voltage Range	0 ~ ±10Vdc / 0 ~ ±600%															
		Impedance	10KΩ															
	Accel/Decel. Time Constant		Linear:0 ~ 50sec ; Ripple:0 ~ 10sec															
	Speed Limit Operation		External analog command / Set by internal parameters															
Torque Reach Range		0 ~ 300% (Set by internal parameters)																
Input/ Output Signal	Position Output	Output Type	Phase A, B, Z Line Drive /Phase Z Open Collector															
		Encoder Ratio	Pulse Output: 1 ~ encoder—pulse numbers (any arbitrary values set by Internal parameters)															
	Digital Input [NPN/PNP]	Programmable 12 points	Servo on, Alarm reset, P/Pl switching, CCW/CW switch limited, External torque limit, Pulse deviation clear, Servo lock, Emergency stop, Speed command selection, Control mode switching, Pulse command inhibit, Gain switching, Electric gear ratio setting, Internal pulse command trigger, Internal pulse command pause, Homing, External reference signal, Internal position command selection, Torque/Speed command reverse, Forward/Reverse operation in torque maod. 31 Types of Optional Functions															
	Digital Output Photocoupler	Programmable 4 points	Servo alarm code, P mode enable, Torque limit, Drive disable, Base Block. Fix Output Alarm Code															
		Programmable 4 points	Servo ready, Servo alarm, Zero speed, Brake interlock, Speed reach, Position completed, Homing completed, Torque reach. 17 Types of Optional Functions															
Analog Output Signal	Programmable 3 points	Speed feedback, Torque/Speed/Pulse input command, Position deviationvalue, electrical angle, Main circuit voltage (Vdc Bus). 12 Types of Optional Functions (0~±10Vdc)																
Environment	Installation site		Indoor (avoiding direct sunshine)															
			no erosion air (avoiding oil gases, inflammable gas and dust)															
	Altitude		Sea level 1000m below															
	Temperature		Operating Temperature 0~ 50℃ , storage Temperature: -20 ~ +65℃															
	Humidity		Operating, storage below 90% RH															
Vibration		10 ~ 57Hz : 20m/s ² ; 57 ~ 150Hz : 2G																
Certification			In compliance with EN61800-3 and EN61800-5-1															
	CE UL		UL508C															

System Configuration





Servo Motor JSMA Series

IP67

Model Designation

JS

TECO AC Servo Series

M

Servo Motor

A

Series:

AP: A Series

P

IP67 (except shaft and connectors)

S

Inertia:

S: Super Low

L: Low

M: Middle

H: Middle

C

Motor Speed:

A: 1000rpm

B: 2000rpm

C: 3000rpm

H: 1500rpm

08

Rated Output Power:

P5 : 50W

01 : 100W

02 : 200W

03 : 300W

04 : 400W

05 : 500W

08 : 750W

10 : 1kW

15 : 1.5kW

20 : 2kW

30 : 3kW

45 : 4.5KW

56 : 5.6KW

75 : 7.5kW

110 : 11 kW

A

Input Voltage:

A : 200V Class

B : 400V Class

H

Encoder Resolution:

B: 2500ppr

7: 17-bit

5: 15-bit(absolute)

A: 17-bit(absolute)

Mechanical Brake:

: without brake

B : with brake(24VDC)

For Internal Management:

or 01

01

No.	Keyway	Oil seal
	No	No
K	Yes	No
O	No	Yes
A	Yes	Yes

*1 The information above is for model description, please contact our sales for more detail.
*2 The encoder options may differ from motors.

Standard Specification

200V Class
S/L Series Low Inertia
(50W~750W)



Motor Mode	Symbol	Unit	JSMA-P□□□□						
			200V Class						
			SCP5A	SC01A	SC02A	SC04A	SC08A	LC03A	LC08A
Standard / Customization			Standard						
Drive Model			10A	10A/15A	10A/15A	15A/20A	20A/30A	15A	20A
Rated Output	P _R	KW	0.05	0.1	0.2	0.4	0.75	0.3	0.75
Rated Torque	T _R	N · m	0.16	0.32	0.64	1.27	2.39	0.95	2.39
Max. Torque	T _{max}	N · m	0.48	0.96	1.91	3.82	7.16	2.85	7.17
Rated Speed	N _R	rpm	3000						
Max. Speed	N _{max}	rpm	4500				3750	4500	3800
Rated Current	I _R	A	0.43	0.94	1.80	2.50	4.30	2.00	3.75
Max. Armature Current	I _{max}	A	1.29	2.82	5.40	7.50	12.90	6.00	11.25
Torque Constant	K _T	N · m/A	0.4	0.38	0.39	0.58	0.61	0.50	0.70
Rotor Moment of Inertia	J _M	Kg · cm ²	0.03	0.04	0.17	0.28	0.94	0.68	2.26
Armature Resistor	R _a	Ω	71.0	25.0	7.50	5.60	2.10	5.00	2.18
Armature Inductance	L _a	mH	78.0	35.0	16.2	14.5	8.6	11.6	7.7
Mechanical Time Constant	T _m	ms	1.81	0.93	0.80	0.69	0.80	1.98	1.50
Electrical Time Constant	T _e	ms	1.10	1.40	2.16	2.59	4.11	2.23	3.53
Weight(Standard)	W	kgw	0.48	0.70	1.03	1.37	2.54	1.58	3.2
Insulation Grade	—	—	Class B(130℃)			Class F(155℃)			
Operating Ambient Temp.	T	℃	0~40						
Operating Ambient Humidity	RH	%	<80						
Storage Temp.	T	℃	-20~60						
Storage Humidity	RH	%	<80						

1(kgf · cm)=0.0980665(N · m) ; 1(gf · cm · s²)=0.980665(kg · cm²)

Standard Specification

200V Class
M series Medium inertia
(550W~3kW)



Motor Mode	Symbol	Unit	JSMA-P 						
			200V Class						
			MA05A	MA10A	MA15A	MB10A	MB15A	MB20A	MB30A
Standard / Customization			Standard						
Drive Model			20A	30A	50A3	30A	50A3	50A3	75A3
Rated Output	P _R	KW	0.55	1.0	1.5	1.0	1.5	2.0	3.0
Rated Torque	T _R	N · m	5.25	9.55	14.32	4.77	7.16	9.55	14.32
Max. Torque	T _{max}	N · m	15.75	28.65	42.96	14.31	21.48	28.65	42.96
Rated Speed	N _R	rpm	1000			2000			
Max. Speed	N _{max}	rpm	1500	1350	1250	2800		2500	
Rated Current	I _R	A	3.3	5.1	7.3	5.1	7.3	9.0	13.7
Max. Armature Current	I _{max}	A	9.9	15.3	21.9	15.3	21.9	27.0	41.4
Torque Constant	K _T	N · m/A	1.68	2.04	2.11	1.02	1.06	1.14	1.13
Rotor Moment of Inertia	J _M	Kg · cm ²	6.26	12.14	17.92	6.26	8.88	12.14	17.92
Armature Resistor	R _a	Ω	3.58	1.85	1.19	1.22	0.79	0.58	0.33
Armature Inductance	L _a	mH	18.3	12.1	8.4	6.7	4.7	3.8	2.1
Mechanical Time Constant	T _m	ms	1.19	0.81	0.72	1.10	0.98	0.80	0.70
Electrical Time Constant	T _e	ms	5.12	6.55	7.09	5.49	6.00	6.52	6.38
Weight(Standard)	W	kgw	6.47	10.16	13.87	6.47	8.08	10.16	13.87
Insulation Grade	—	—	Class B(130℃)						
Operating Ambient Temp.	T	℃	0~40						
Operating Ambient Humidity	RH	%	<90						
Storage Temp.	T	℃	-20~60						
Storage Humidity	RH	%	<90						

1(kgf · cm)=0.0980665(N · m) ; 1(gf · cm · s³)=0.980665(kg · cm³)

Motor Mode	Symbol	Unit	JSMA-P□□□□					
			200V Class					
			MH05A	MH10A	MC10A	MC15A	MC20A	MC30A
Standard / Customization			Customization					
Drive Model			20A	30A	30A	50A3	50A3	75A3
Rated Output	P _R	KW	0.55	1.0	1.0	1.5	2.0	3.0
Rated Torque	T _R	N · m	3.50	6.40	3.20	4.77	6.37	9.55
Max. Torque	T _{max}	N · m	10.50	19.21	9.60	14.31	19.11	28.65
Rated Speed	N _R	rpm	1500		3000			
Max. Speed	N _{max}	rpm	2000		3700		3850	
Rated Current	I _R	A	2.98	5.00	4.96	6.90	9.30	13.70
Max. Armature Current	I _{max}	A	8.94	15.00	14.88	20.70	27.90	41.10
Torque Constant	K _T	N · m/A	1.29	1.41	0.72	0.74	0.74	0.75
Rotor Moment of Inertia	J _M	Kg · cm ²	6.26	12.14	4.60	6.26	8.88	12.14
Armature Resistor	R _a	Ω	2.31	0.95	1.02	0.65	0.40	0.25
Armature Inductance	L _a	mH	10.8	8.8	5.1	3.6	2.4	1.6
Mechanical Time Constant	T _m	ms	1.29	0.89	1.39	1.12	0.98	0.80
Electrical Time Constant	T _e	ms	4.68	9.28	4.96	5.48	6.00	6.56
Weight(Standard)	W	kgw	6.49	10.18	5.29	6.47	8.08	10.16
Insulation Grade	—	—	Class B(130℃)					
Operating Ambient Temp.	T	℃	0~40					
Operating Ambient Humidity	RH	%	<90					
Storage Temp.	T	℃	-20~60					
Storage Humidity	RH	%	<90					

1(kgf · cm)=0.0980665(N · m) ; 1(gf · cm · s³)=0.980665(kg · cm³)

Standard Specification

200V Class LH series Low inertia (3kW~11kW)



Motor Mode	Symbol	Unit	JSMA-□□□□				
			200V Class				
			LH30A	LH45A	LH56A	LH75A	LH110A
Standard / Customization			Standard				
Drive Model			75A3	100A3	150A3	200A3	300A3
Rated Output	P _R	KW	3.0	4.5	5.6	7.5	11.0
Rated Torque	T _R	N · m	19.10	28.80	34.90	48.00	70.00
Max. Torque	T _{max}	N · m	57.30	63.40	87.20	144.0	210.0
Rated Speed	N _R	rpm	1500				
Max. Speed	N _{max}	rpm	1800				
Rated Current	I _R	A	17.7	25.10	33.00	53.40	77.90
Max. Armature Current	I _{max}	A	53.10	56.30	84.20	160.2	233.7
Torque Constant	K _T	N · m/A	1.08	1.18	1.15	1.19	1.10
Rotor Moment of Inertia	J _M	Kg · cm ²	23.66	31.60	41.5	73.00	109.8
Armature Resistor	R _a	Ω	0.18	0.23	0.18	0.04	0.03
Armature Inductance	L _a	mH	4.0	3.1	2.4	0.8	0.5
Mechanical Time Constant	T _m	ms	0.35	0.50	0.58	0.27	0.26
Electrical Time Constant	T _e	ms	21.9	15.09	13.17	20.23	20.40
Weight(Standard)	W	kgw	12.1	15.70	16.80	24.50	33.40
Insulation Grade	—	—	Class F (155℃)				
Operating Ambient Temp.	T	℃	0 ~ 40				
Operating Ambient Humidity	RH	%	<90				
Storage Temp.	T	℃	-20 ~ 60				
Storage Humidity	RH	%	<90				

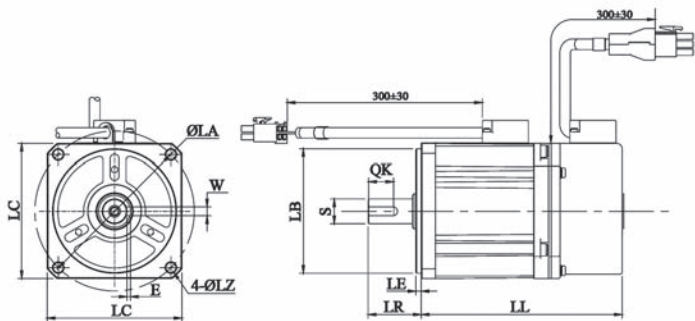
1(kgf · cm)=0.0980665(N · m) ; 1(gf · cm · s)=0.980665(kg · cm²)

400V Class MB/LH series Medium / Low inertia (1kW~7.5kW)

Motor Mode	Symbol	Unit	JSMA-P□□□□				JSMA-□□□□			
			400V Class							
			MB10B	MB15B	MB20B	MB30B	LH30B	LH45B	LH56B	LH75B
Standard / Customization			Standard							
Drive Model			25B	25B	35B	50B	50B	75B	75B	100B
Rated Output	P _R	KW	1.0	1.5	2.0	3.0	3.0	4.5	5.6	7.5
Rated Torque	T _R	N · m	4.77	7.16	9.55	14.32	19.1	28.6	34.7	48.0
Max. Torque	T _{max}	N · m	14.31	21.48	28.65	42.96	57.3	85.8	104.1	144.0
Rated Speed	N _R	rpm	2000				1500			
Max. Speed	N _{max}	rpm	2800		2500		1800			
Rated Current	I _R	A	2.58	4.36	5.9	8.90	11.5	17.00	19.00	28.7
Max. Armature Current	I _{max}	A	7.74	13.1	17.7	26.7	34.5	51.0	57.0	86.1
Torque Constant	K _T	N · mA	1.98	1.80	1.76	1.78	1.66	1.68	1.82	1.67
Rotor Moment of Inertia	J _M	Kg · cm ²	6.26	8.88	12.1	17.9	23.7	31.6	41.5	73.0
Armature Resistor	R _a	Ω	5.38	2.42	1.45	0.83	0.75	0.42	0.30	0.13
Armature Inductance	L _a	mH	27.4	13.0	9.0	5.9	11.5	7.3	5.5	2.8
Mechanical Time Constant	T _m	ms	1.28	0.99	0.84	0.70	0.60	0.45	0.38	0.31
Electrical Time Constant	T _e	ms	5.09	5.37	6.18	7.10	15.29	17.17	18.63	22.19
Weight(Standard)	W	kgw	6.47	8.08	10.16	13.87	11.9	14.2	16.3	24.5
Insulation Grade	—	—	Class B(130℃)				Class F(155℃)			
Operating Ambient Temp.	T	℃	0 ~ 40							
Operating Ambient Humidity	RH	%	<90							
Storage Temp.	T	℃	-20 ~ 60							
Storage Humidity	RH	%	<90							

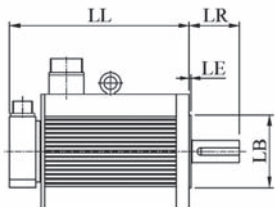
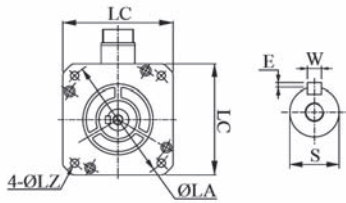
1(kgf · cm)=0.0980665(N · m) ; 1(gf · cm · s)=0.980665(kg · cm²)

Dimension

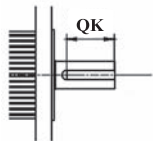


Servo Motor Model		LZ ϕ	La ϕ	LC	E	W	S ϕ	LB ϕ	QK	LE	LR	LL	
200V Class	Without Brake	LC03A	5.5	90	76	2	5	14	70	20	3	30	112.9
		LC08A	6.5	100	86	2	5	16	80	25	3	35	147.5
	With Brake	LC03A	5.5	90	76	2	5	14	70	20	3	30	147.3
		LC08A	6.5	100	86	2	5	16	80	25	3	35	182.7
	Without Brake	SCP5A	3.5	48	42	-	-	8	30	16	2.5	25.5	85.3
		SC01A	3.5	48	42	-	-	8	30	16	2.5	25	106.3
		SC02A	5.5	70	60	2	5	14	50	22	3	30	112.8
		SC04A	5.5	70	60	2	5	14	50	22	3	30	132.8
		SC08A	5.5	90	80	2.5	6	19	70	30	3	40	139.0
		SC01A	3.5	48	42	-	-	8	30	16	2.5	25	143.6
	With Brake	SC02A	5.5	70	60	2	5	14	50	22	3	30	147.3
		SC04A	5.5	70	60	2	5	14	50	22	3	30	167.3
		SC08A	5.5	90	80	2.5	6	19	70	30	3	40	174.0

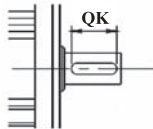
Unit:mm



MA/MB/MC Series



LH Series



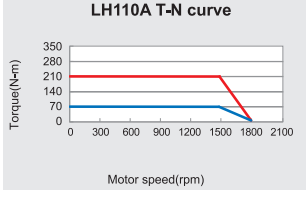
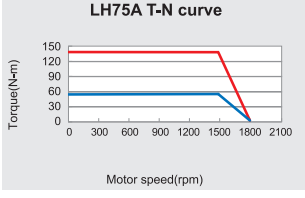
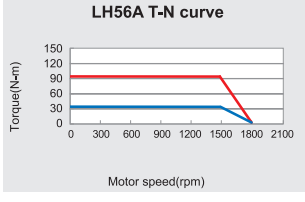
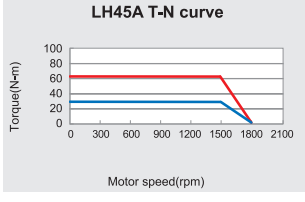
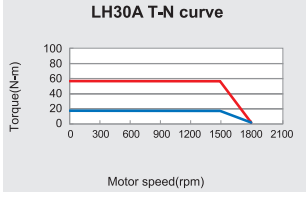
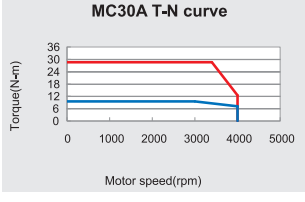
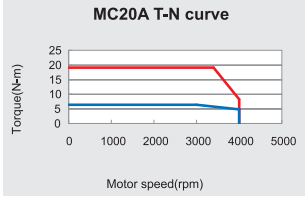
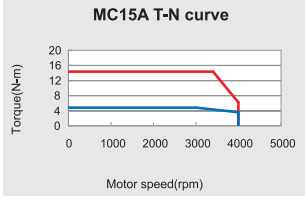
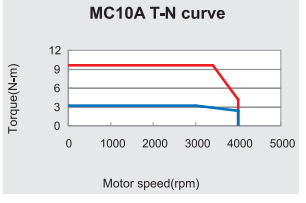
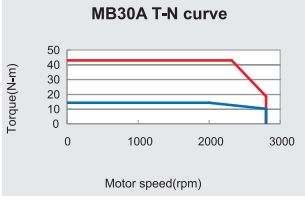
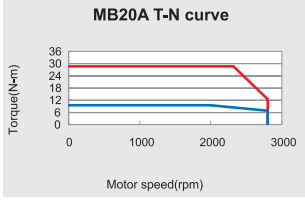
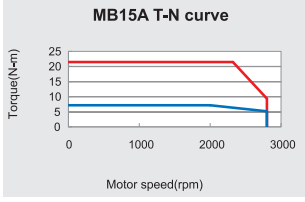
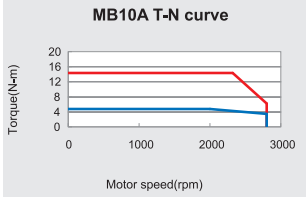
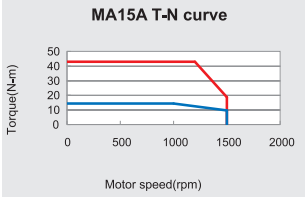
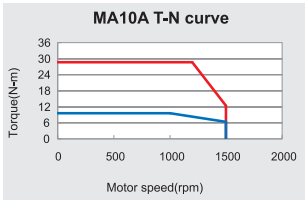
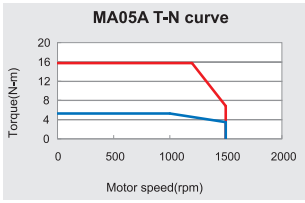
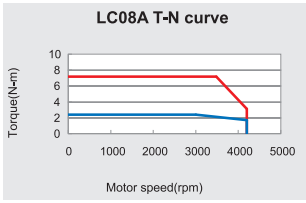
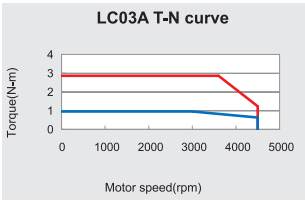
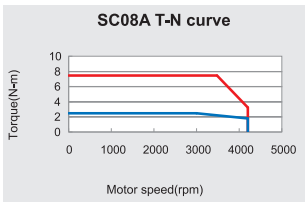
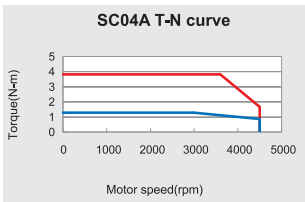
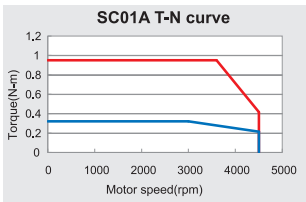
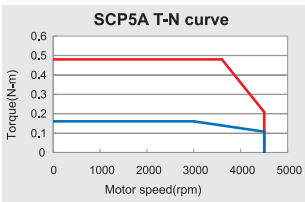
Servo Motor Model		LZ ϕ	La ϕ	LC	E	W	S ϕ	LB ϕ	QK	LE	LR	LL	
200V Class	Without Brake	MA05A	9	145	130	2.5	6	22	110	35	6	58	163.8
		MH05A	9	145	130	2.5	6	22	110	35	6	58	163.8
		MA10A	9	145	130	2.5	6	22	110	35	6	58	213.8
		MB10A	9	145	130	2.5	6	22	110	35	6	58	163.8
		MC10A	9	145	130	2.5	6	22	110	35	6	58	148.8
		MH10A	9	145	130	2.5	6	22	110	35	6	58	213.8
		MA15A	9	145	130	2.5	6	22	110	35	6	58	263.8
		MB15A	9	145	130	2.5	6	22	110	35	6	58	183.8
		MC15A	9	145	130	2.5	6	22	110	35	6	58	163.8
		MB20A	9	145	130	2.5	6	22	110	35	6	58	213.8
		MC20A	9	145	130	2.5	6	22	110	35	6	58	184.8
		MB30A	9	145	130	2.5	6	22	110	35	6	58	263.8
		MC30A	9	145	130	2.5	6	22	110	35	6	58	213.8
		LH30A	13.5	200	180	3	10	35	114	70	3	80	173.2
		LH45A	13.5	200	180	3	10	35	114	70	3	80	186.2
		LH56A	13.5	200	180	3	10	35	114	70	3	80	202.2
		LH75A	13.5	200	180	3	10	35	114	70	3	80	252.2
		LH110A	13.5	200	180	3	10	35	114	70	3	80	312.2
	With Brake	MA05A	9	145	130	2.5	6	22	110	35	6	58	218.3
		MH05A	9	145	130	2.5	6	22	110	35	6	58	218.3
		MA10A	9	145	130	2.5	6	22	110	35	6	58	268.3
		MB10A	9	145	130	2.5	6	22	110	35	6	58	218.3
		MC10A	9	145	130	2.5	6	22	110	35	6	58	203.3
		MH10A	9	145	130	2.5	6	22	110	35	6	58	268.3
		MA15A	9	145	130	2.5	6	22	110	35	6	58	318.3
		MB15A	9	145	130	2.5	6	22	110	35	6	58	238.3
		MC15A	9	145	130	2.5	6	22	110	35	6	58	218.3
		MB20A	9	145	130	2.5	6	22	110	35	6	58	268.3
		MC20A	9	145	130	2.5	6	22	110	35	6	58	238.3
		MB30A	9	145	130	2.5	6	22	110	35	6	58	318.3
		MC30A	9	145	130	2.5	6	22	110	35	6	58	268.3
		LH30A	13.5	200	180	3	10	35	114	70	3	80	210.9
		LH45A	13.5	200	180	3	10	35	114	70	3	80	223.9
		LH56A	13.5	200	180	3	10	35	114	70	3	80	239.9
		LH75A	13.5	200	180	3	10	35	114	70	3	80	312.2
		LH110A	13.5	200	180	3	10	35	114	70	3	80	381.2
400V Class	Without Brake	MB10B	9	145	130	2.5	6	22	110	35	6	58	163.8
		MB15B	9	145	130	2.5	6	22	110	35	6	58	183.8
		MB20B	9	145	130	2.5	6	22	110	35	6	58	213.8
		MB30B	9	145	130	2.5	6	22	110	35	6	58	263.8
		LH30B	13.5	200	180	3	10	35	114	70	3	80	173.2
		LH45B	13.5	200	180	3	10	35	114	70	3	80	186.2
		LH56B	13.5	200	180	3	10	35	114	70	3	80	202.2
		LH75B	13.5	200	180	3	10	35	114	70	3	80	252.2
		With Brake	MB10B	9	145	130	2.5	6	22	110	35	6	58
	MB15B		9	145	130	2.5	6	22	110	35	6	58	238.3
	MB20B		9	145	130	2.5	6	22	110	35	6	58	268.3
	MB30B		9	145	130	2.5	6	22	110	35	6	58	318.3
	LH30B		13.5	200	180	3	10	35	114	70	3	80	210.9
	LH45B		13.5	200	180	3	10	35	114	70	3	80	223.9
	LH56B		13.5	200	180	3	10	35	114	70	3	80	239.9
	LH75B		13.5	200	180	3	10	35	114	70	3	80	312.2

Unit:mm

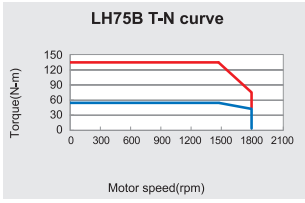
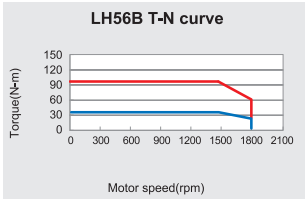
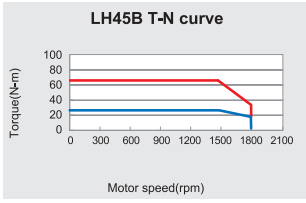
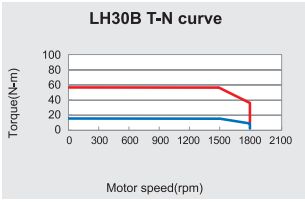
Performance Curve

200V Class

Intermittent duty
Continuous duty

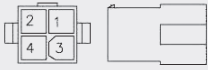


400V Class

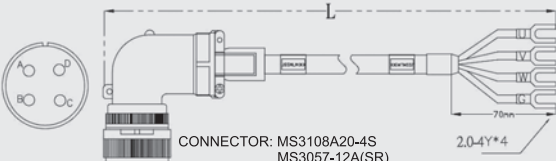
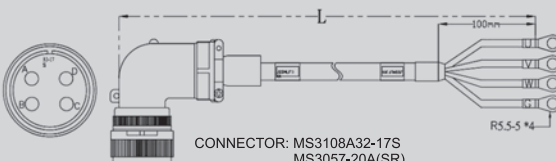


Accessories

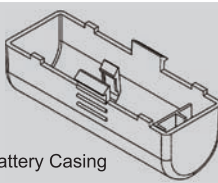
Power Connectors

Part No.	Description	Model
JSSCNM04	For JSMA-S/L Series (50W~750W)	 CAP: 172159-1 SCOKET: 170362-1
JSSCNML04	For JSMA-M Series without brake (550W~3kW)	 CONNECTOR: MS3108A20-4S MS3057-12A(SR)
JSSCNBL04	For JSMA-LH Series without brake (3kW~15kW)	 CONNECTOR: MS3108A32-17S MS3057-20A(SR)
JSSCNML07	For JSMA-M Series with brake (550W~3kW)	 CONNECTOR: MS3108A20-15S MS3057-12A(SR)
JSSCNBS03	For JSMA-LH brake (3kW~15kW)	 CONNECTOR: MS3106A10SL-3S MS3057-4A(SR)

Power Cables

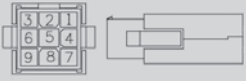
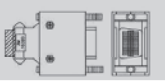
Part No.	L (Meter)	Description	Model
JSSLM001	1	For JSMA-S/L Series (50W~750W)	 CAP: 172159-1 SCOKET: 170362-1
JSSLM003	3		
JSSLM005	5		
JSSLM010	10		
JSSLM015	15		
JSSLM020	20		
JSSMLM001	1	For JSMA-M Series without brake (550W~3kW)	 CONNECTOR: MS3108A20-4S MS3057-12A(SR)
JSSMLM003	3		
JSSMLM005	5		
JSSMLM010	10		
JSSMLM015	15		
JSSMLM020	20		
JSSBLM001	1	For JSMA-LH/MH Series without brake (3kW~5.6kW)	 CONNECTOR: MS3108A32-17S MS3057-20A(SR)
JSSBLM003	3		
JSSBLM005	5		
JSSBLM010	10		
JSSBLM015	15		
JSSBLM020	20		

Battery Module (For JSDA+ Series)

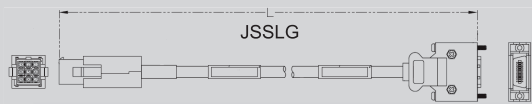
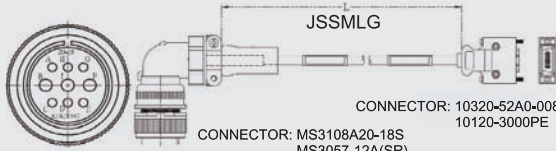
Part No.	Description	Model
JSSBAT	For absolute encoder	 Battery Casing  Battery

Accessories

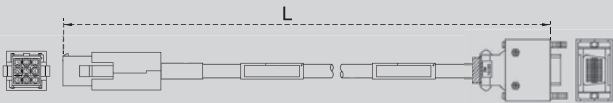
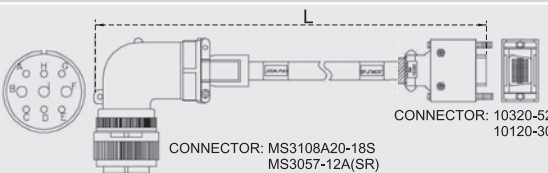
Encoder Connectors

Part No.	Description	Model
JSSCNP09	For JSMA-S/L Series	 CONNECTOR: 172161-1 TERMINAL: 170361-1
JSSCNPL09	For JSMA-M Series	 CONNECTOR: MS3108A20-18S MS3057-12A(SR)
JSSCN20P	For JSDA+ Series (CN2)	 CONNECTOR: 10320-52A0-008 12120-3000PE
JSSECN09P	For JSDE+ Series (CN2)	 CONNECTOR: D-SUB9PM Male COVER: DC-9CT Screw

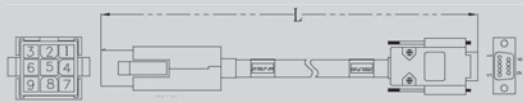
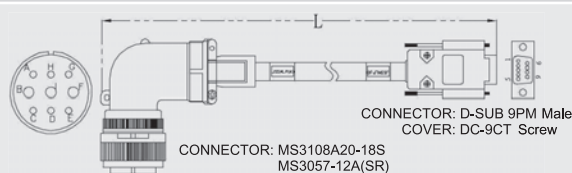
Encoder Cables (For JSDA+ Series 15-bit / 17-bit encoders)

Part No.	L (Meter)	Description	Model
JSSLG001	1	For JSMA-S/L Series and JSDA+ Series	 JSSLG CONNECTOR: 172161-1 TERMINAL: 170361-1 CONNECTOR: 10320-52A0-008 10120-3000PE
JSSLG003	3		
JSSLG005	5		
JSSLG010	10		
JSSLG015	15		
JSSLG020	20		
JSSMLG001	1	For JSMA-M Series and JSDA+ Series	 JSSMLG CONNECTOR: MS3108A20-18S MS3057-12A(SR) CONNECTOR: 10320-52A0-008 10120-3000PE
JSSMLG003	3		
JSSMLG005	5		
JSSMLG010	10		
JSSMLG015	15		
JSSMLG020	20		

Encoder Cables (For JSDA+ Series 2500ppr / 8192ppr encoders)

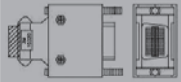
Part No.	L (Meter)	Description	Model
JSSLP001	1	For JSMA-S / L Series and JSDA+ Series	 L CONNECTOR: 172161-1 TERMINAL: 170361-1 CONNECTOR: 10320-52A0-008 10120-3000PE
JSSLP003	3		
JSSLP005	5		
JSSLP010	10		
JSSLP015	15		
JSSLP020	20		
JSSMLP001	1	For JSMA-M Series and JSDA+ Series	 L CONNECTOR: MS3108A20-18S MS3057-12A(SR) CONNECTOR: 10320-52A0-008 10120-3000PE
JSSMLP003	3		
JSSMLP005	5		
JSSMLP010	10		
JSSMLP015	15		
JSSMLP020	20		

Encoder Cables (For JSDE+ Series 2500ppr / 8192ppr encoders)

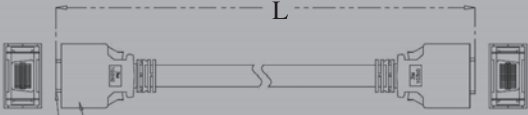
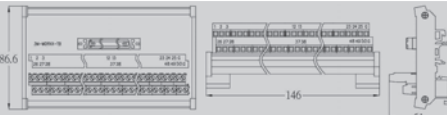
Part No.	L (Meter)	Description	Model
JSELP001	1	For JSMA-S/L Series and JSDE+ Series	 L CONNECTOR: 172161-1 TERMINAL: 170361-1 CONNECTOR: D-SUB 9P Male COVER: DC-9CT Screw
JSELP003	3		
JSELP005	5		
JSELP010	10		
JSELP015	15		
JSELP020	20		
JSEMLP001	1	For JSMA-M Series and JSDE+ Series	 L CONNECTOR: MS3108A20-18S MS3057-12A(SR) CONNECTOR: D-SUB 9PM Male COVER: DC-9CT Screw
JSEMLP003	3		
JSEMLP005	5		
JSEMLP010	10		
JSEMLP015	15		
JSEMLP020	20		

Accessories

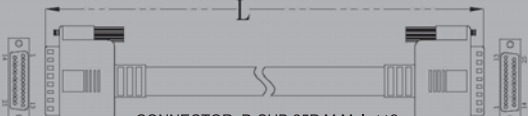
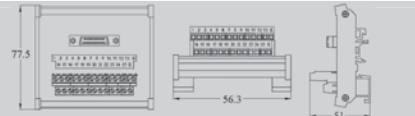
I/O Signal Connectors

Part No.	Description	Model
JSSCN50P	For JSDA ⁺ Series (CN1)	 CONNECTOR: 10350-52A0-008 10150-3000PE
JSSECN25P	For JSDE ⁺ Series (CN1)	 CONNECTOR: D-SUB 25P M Male COVER: DC-25 CT Screw

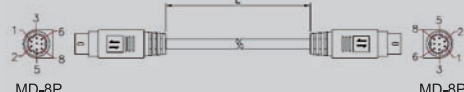
Terminal Block (For JSDA⁺ Series)

Part No.	L (Meter)	Description	Model
JSSTBC0P5	0.5	For JSDA ⁺ Series	 Shell kit: 10350-3210-000*2 SCSI II: 10150-600PE*2
JSSTBC001	1		
JSSTBC002	2		
JSSTB50P	—	For JSDA ⁺ Series	

Terminal Block (For JSDE⁺ Series)

Part No.	L (Meter)	Description	Model
JSSETBC0P5	0.5	For JSDE ⁺ Series	 CONNECTOR: D-SUB 25P M Male X 2 COVER: DC-25 CT Screw X 2
JSSETBC001	1		
JSSETBC002	2		
JSSETB25P	—	For JSDE ⁺ Series	

Communication Cables

Part No.	L (Meter)	Description	Model
JSSDTC001	1	Connection to PC	 D-9S MD-8P
JSSDTC002	2		
JSSDTD001	1	Connection to Drive	 MD-8P MD-8P
JSSDTD002	2		

Distributor



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Specifications covered in this brochure may be subject to change without notice.



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